

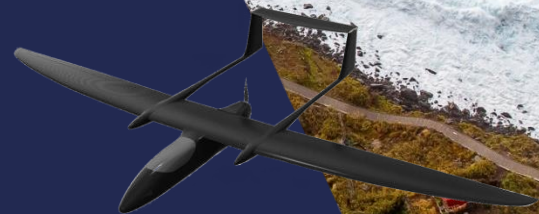
# Manufacturing, mechanical simulations and wing optimization

Dipl. Ing. M. LEFEBVRE

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## Content

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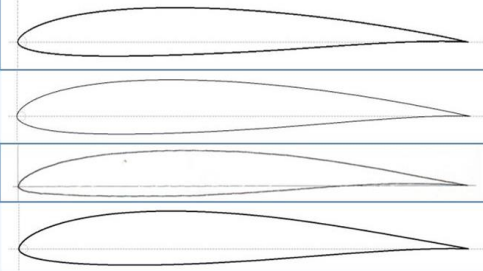
- Wing design - How to choose the wing profile?
- Drone manufacturing
  - Composite manufacturing, composite molding
  - Additive manufacturing
  - Final version manufacturing
- Material analysis
  - Composite material characterization
  - Experimental wing simulation
  - Wing joiner experimental test
- CFD Simulations
  - To design the drone
  - To compare geometries

HN 1023

HN 1091

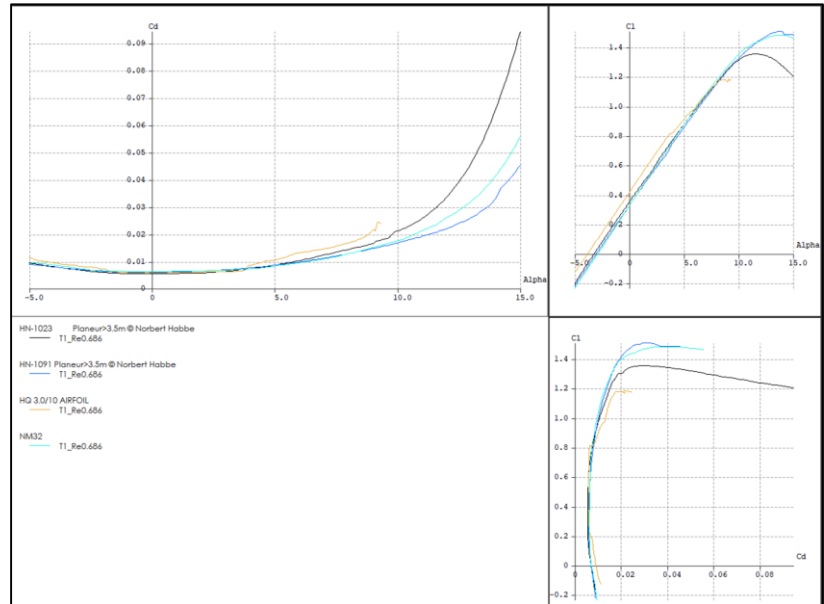
HQ 3,0/10

NM 32

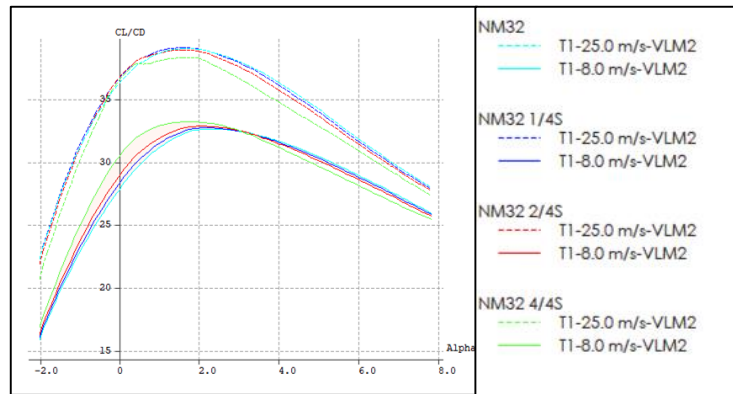


Wing profiles for glider geometry

- Comparison between 4 wing profiles
- Best Lift-to-drag ratio
- latest stall
- Profile selected:  
**NM32**



Wing profile polar curves



Optimization of the wing profile

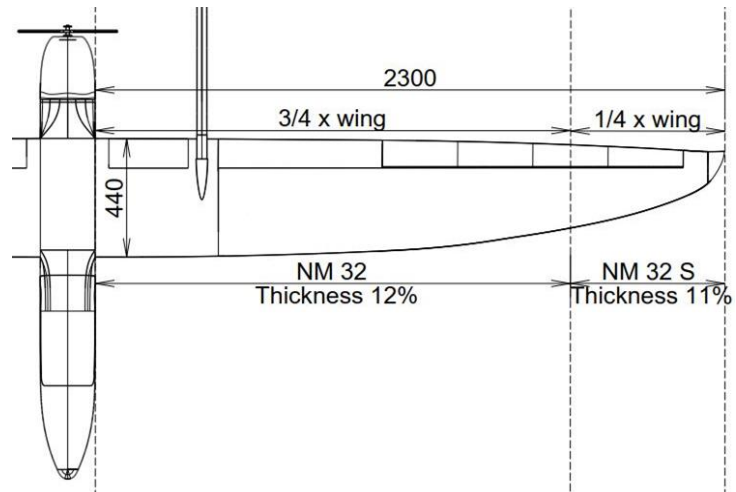
- Wing design:

$\frac{3}{4}$  NM32

$\frac{1}{4}$  NM32 S

→ To do not affect the L to D ratio at high speed

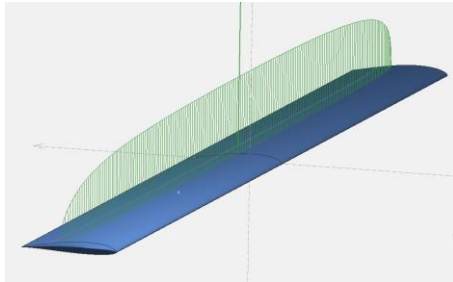
→ To get **elliptic lift distribution**



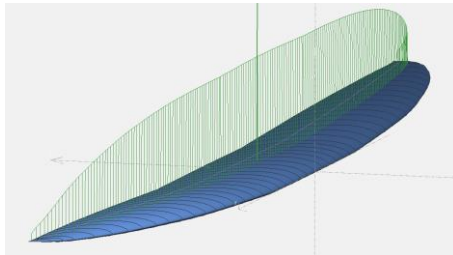
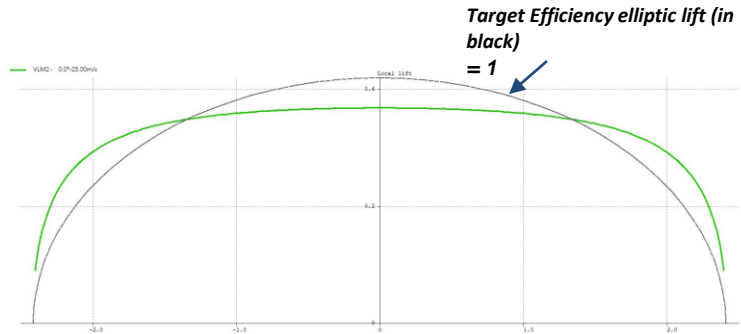
Sketch of the wing profile optimized

# Wing design

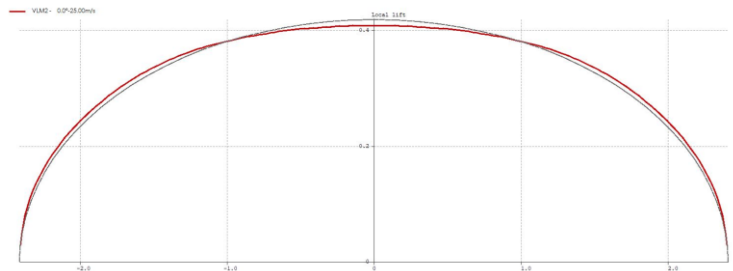
## Elliptic lift distribution?



Rectangular wing - Lift repartition in green



Elliptic wing - Lift repartition in red



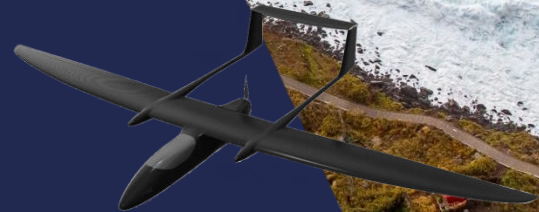
# Drone manufacturing

Structure of the wing - sandwich composite

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# Drone manufacturing

Different process:

- **Composite manufacturing**
  - Vacuum technology
  - Composite molding
- **Additive manufacturing**
  - Testing different shape
  - Low price
  - Low density



Vacuum Laminating (Wing, elevator, rudder)



Fuselage composite molding

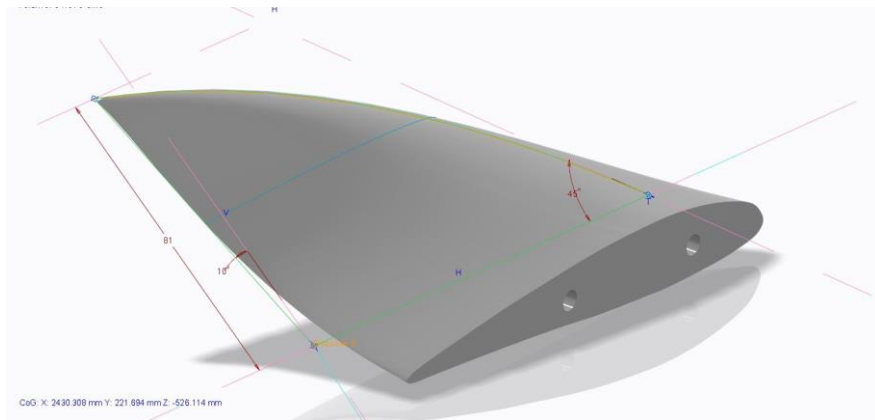
# Drone manufacturing

Different process:

- Composite manufacturing
  - Vacuum technology
  - Composite molding
- Additive manufacturing
  - Testing different shape
  - Low price
  - Low density



Additive Manufacturing



Wingtip CAD to print



# From the prototype to the final version

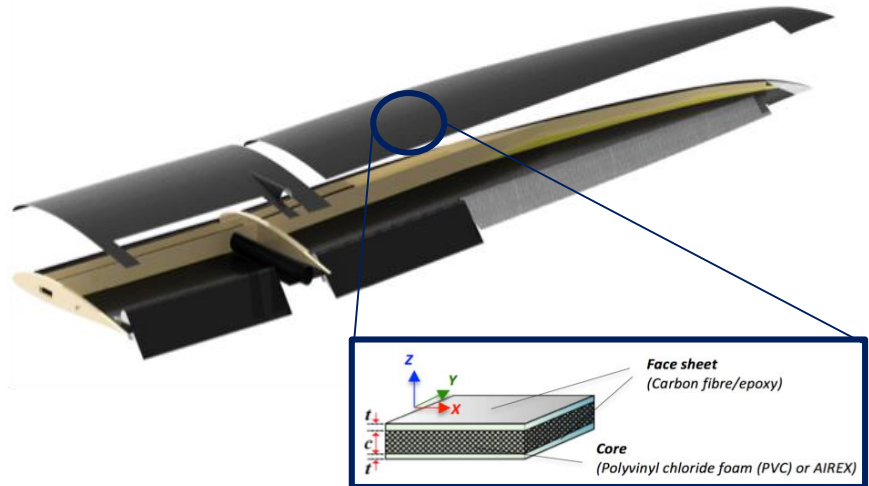
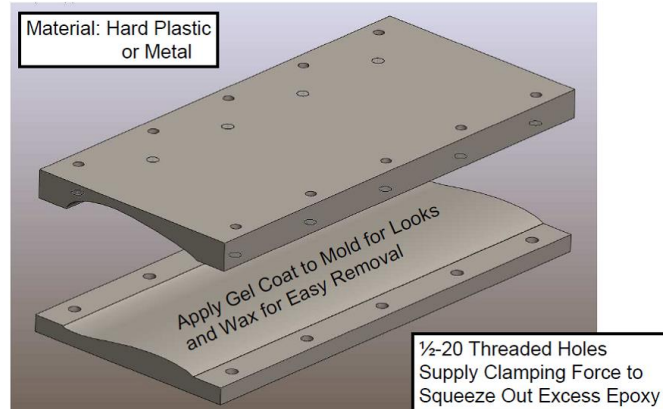
## Material used:

- Structure composite sandwich Carbon fibers/AIREX foam

## Process used:

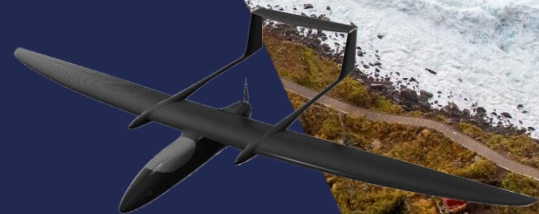
- Composite molding

## Wing mold for final structure



# Material analysis

Structure of the wing - sandwich composite



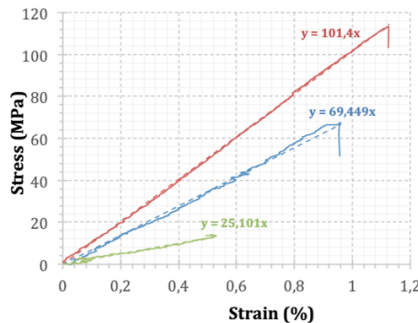
# Composite material characterization

Material used:

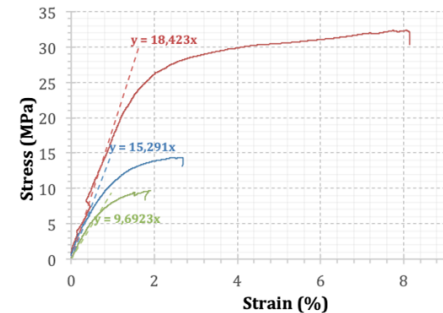
- Structure composite sandwich Carbon fibers/AIREX foam
- Tensile test on sandwich samples

Fiber Orientation: 0° & 45°

## Tensile tests on sandwich samples



— 1.2mm thickness - 0° — 2mm thickness - 0°  
— 5mm thickness - 0°



— 1.2mm thickness - 45° — 2mm thickness - 45°  
— 5mm thickness - 45°

# Comparison between isotropic metal & anisotropic composite

## Composite material characterization

### isotropic metal

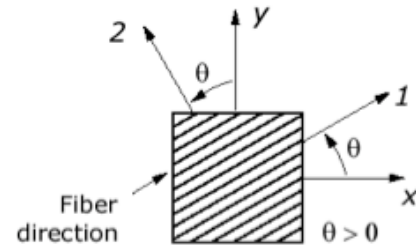
$$\sigma = E\varepsilon$$

- Hooke law
- Same mechanical properties in all directions

- Find mechanical properties of composite material
- Mandatory to study composite material in detail

### anisotropic composite

$$\begin{Bmatrix} \sigma_l \\ \sigma_t \\ \tau_{lt} \end{Bmatrix} = [Q] \begin{Bmatrix} \varepsilon_l \\ \varepsilon_t \\ \gamma_{lt} \end{Bmatrix} = \begin{bmatrix} Q_{11} & Q_{12} & Q_{13} \\ Q_{21} & Q_{22} & Q_{23} \\ Q_{31} & Q_{32} & Q_{33} \end{bmatrix} \begin{Bmatrix} \varepsilon_l \\ \varepsilon_t \\ \gamma_{lt} \end{Bmatrix}$$



With

$$\begin{cases} Q_{11} = \frac{E_l}{(1 - \nu_{lt}\nu_{tl})} \\ Q_{12} = \frac{\nu_{tl}E_l}{(1 - \nu_{lt}\nu_{tl})} \\ Q_{21} = \frac{E_t}{(1 - \nu_{lt}\nu_{tl})} \\ Q_{22} = \frac{\nu_{tl}E_t}{(1 - \nu_{lt}\nu_{tl})} \end{cases}$$

# Comparison between isotropic metal & anisotropic composite



## Composite material characterization

- Find mechanical properties of composite material
- Mandatory to study composite material in detail

### isotropic metal

$$\sigma = E \varepsilon$$

- Hooke law
- Same mechanical properties in all directions

### anisotropic composite

$$\begin{Bmatrix} \sigma_l \\ \sigma_t \\ \tau_{lt} \end{Bmatrix} = [Q] \begin{Bmatrix} \varepsilon_l \\ \varepsilon_t \\ \gamma_{lt} \end{Bmatrix} = \begin{bmatrix} Q_{11} & Q_{12} & Q_{13} \\ Q_{21} & Q_{22} & Q_{23} \\ Q_{31} & Q_{32} & Q_{33} \end{bmatrix} \begin{Bmatrix} \varepsilon_l \\ \varepsilon_t \\ \gamma_{lt} \end{Bmatrix}$$

Matrix behaviour :

$$* A_{ij} = \sum_{k=1}^n Q_{ij}^k e_k$$

$$* B_{ij} = \frac{1}{2} \sum_{k=1}^n Q_{ij}^k (h_k^2 - h_{k-1}^2)$$

$$* D_{ij} = \frac{1}{3} \sum_{k=1}^n Q_{ij}^k (h_k^3 - h_{k-1}^3)$$

$$[N] = \begin{bmatrix} A_{11} & A_{12} & 0 & B_{11} & B_{12} & 0 \\ A_{12} & A_{22} & 0 & B_{12} & B_{22} & 0 \\ 0 & 0 & A_{66} & 0 & 0 & B_{66} \\ \hline B_{11} & B_{12} & 0 & D_{11} & D_{12} & 0 \\ B_{12} & B_{22} & 0 & D_{12} & D_{22} & 0 \\ 0 & 0 & B_{66} & 0 & 0 & D_{66} \end{bmatrix}$$

→ Input for numerical simulations

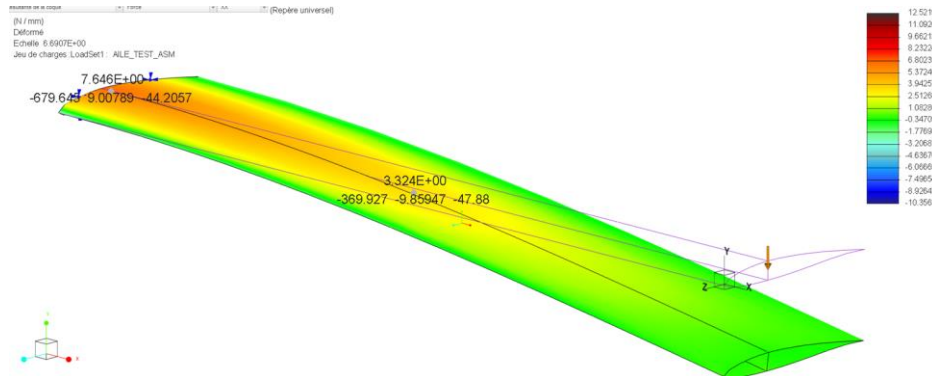
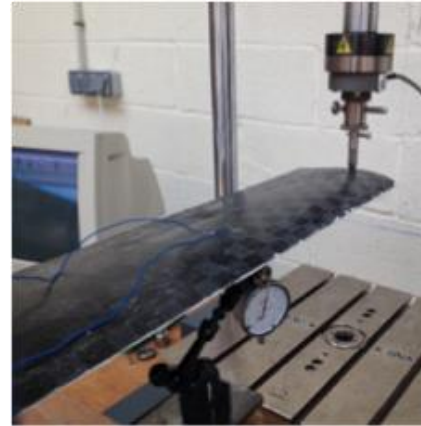
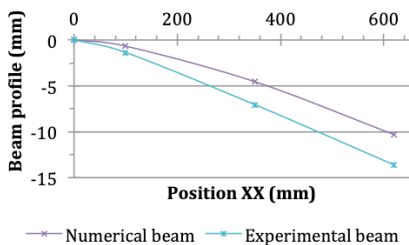
## Comparison between numerical simulation and experimental test

# Composite material simulations

How accurate is the simulation ?

## Comparisons

- Beam in 3 points
  - Stress in 4 points
- (tension/compression)



Measure of the stress (MPa) in numerical simulation

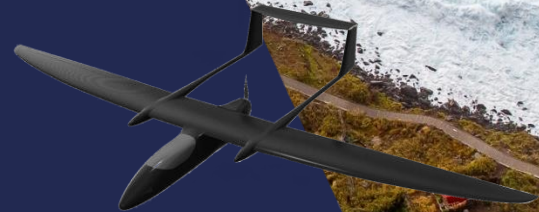
# Material analysis

Wing joiner

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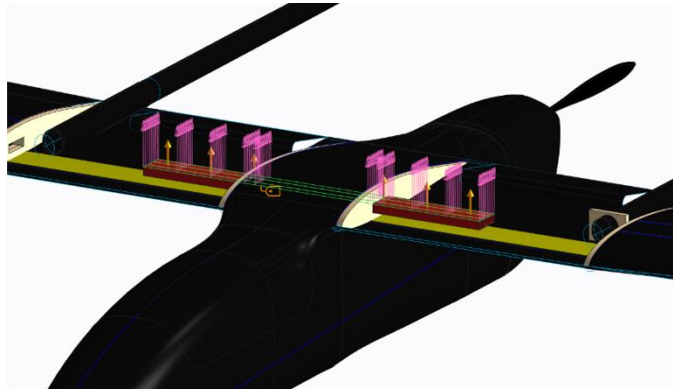




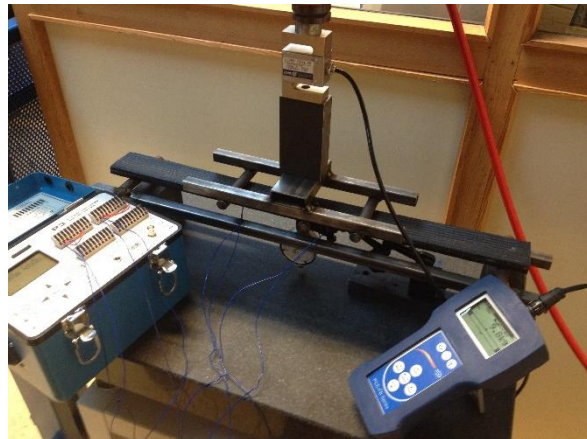
# Strength experiments – 4 points Bending test

To determine material properties:

- Young's modulus
- Failure stress
- Strain



Wing joiner stress

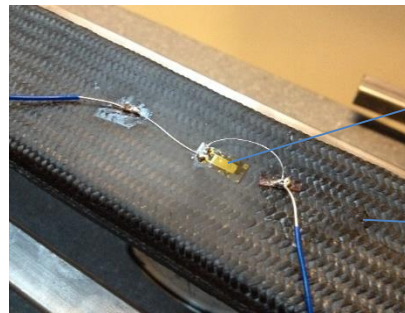


Experimental test bench



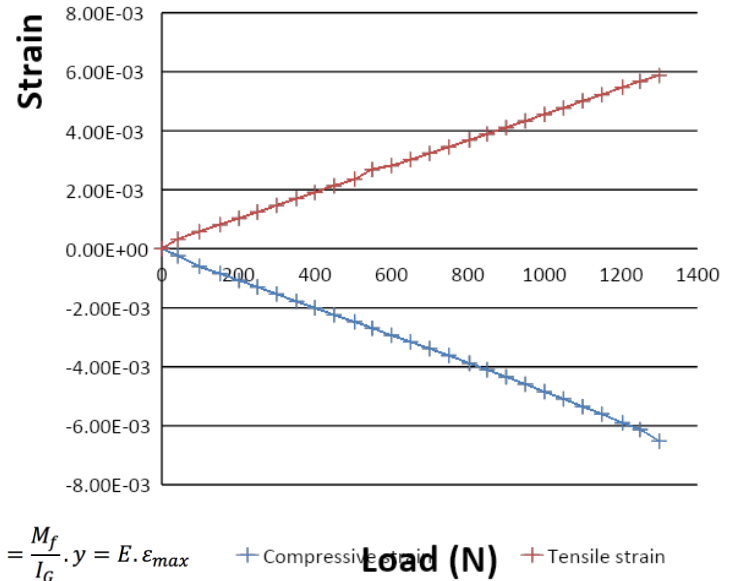
# Bending test – Results : Wing joiner strain

- Determination of the failure stress
- Young's modulus:  
 **$E=15,1 \text{ GPa}$**
- Failure stress:  
 **$\sigma_{\max}=97\text{MPa}$**



Strain gauge

Wing joiner



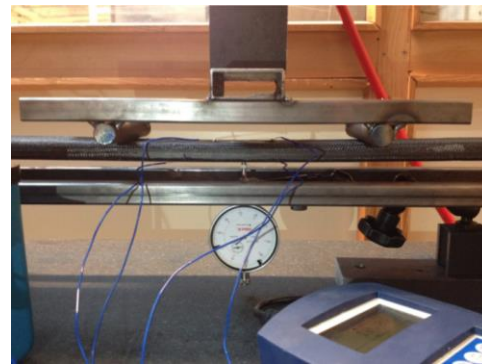
Strain measure (tension & compression)

# Bending test – Data processing

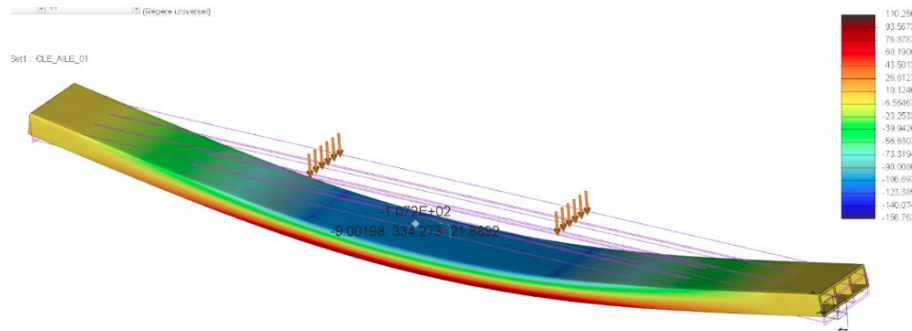
## Goal:

- To use real material properties in computer simulations

**Relative error = 7,6%**  
*(experimental / computer simulation)*



Wing joiner bending test



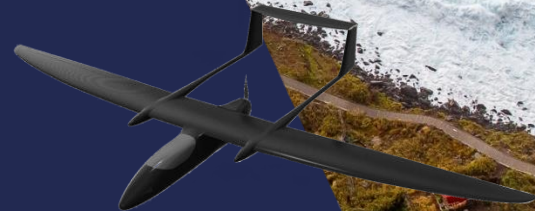
CREO PTC Mechanical simulation

# CFD Simulations

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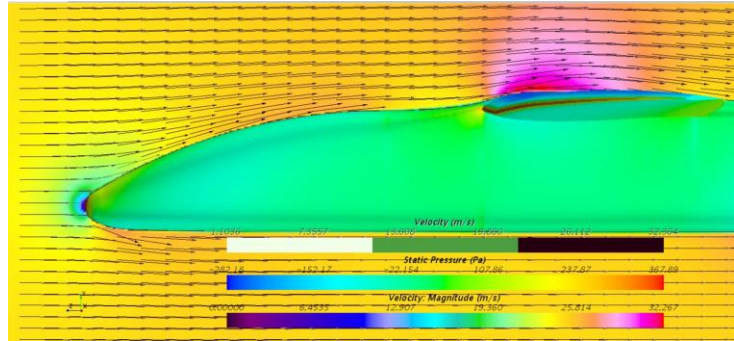
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# CFD Simulation Comparison

## Goal:

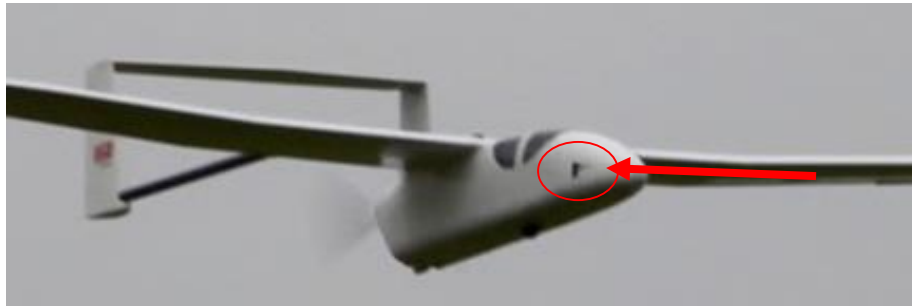
- To improve drone efficiency
- To design the drone
- To compare drones behaviour



Airflow on CFD simulation

CFD Simulations to check the perfect location for:

- Naca inlet (to cool down equipments)
- Pitot tube (parallel to the airflow)

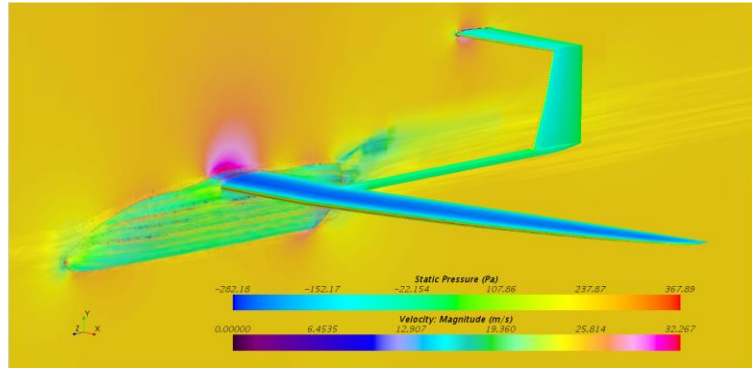


Naca inlet during the flight

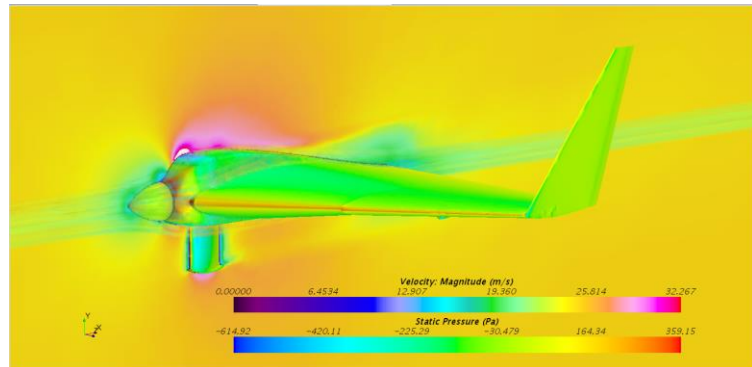
# CFD Simulation Comparison

## Goal:

- To improve drone efficiency
- To design the drone
- To compare drones behaviour



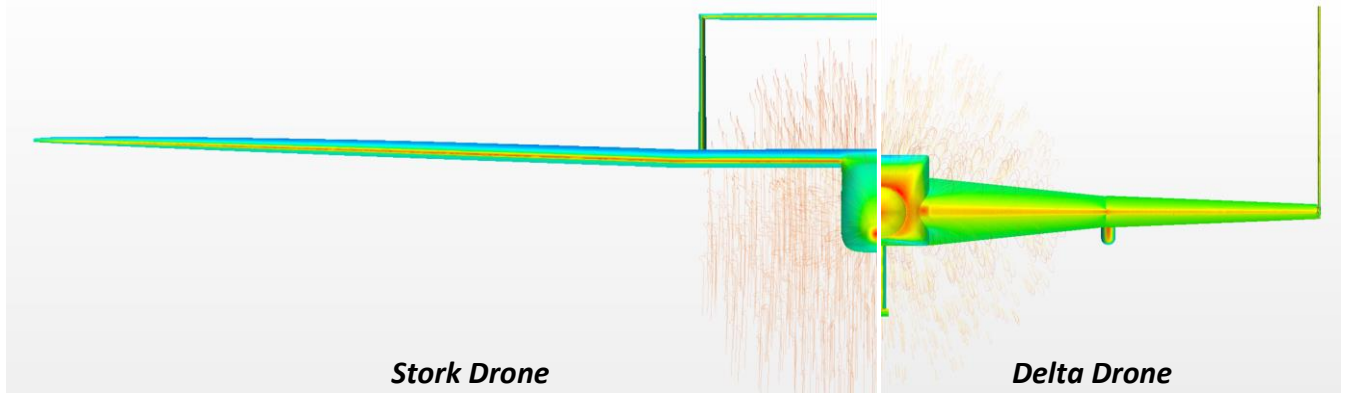
Stork drone - 25m/s



Delta drone - 30 m/s

# CFD Simulation Comparison

*Objective: To compare both geometries with CFD Simulations*



# Further work in mechanical studies

- Integrate equipments for the future missions
- Design & manufacture the molds for the final drone
  - Wings
  - Lateral fuselages
- Study innovative composite material for the drone structure
  - Biobased composite
  - Recycled composite

→ Ph.D. from october 2019

**Thank you for  
your attention!**

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